

NAG Fortran Library Routine Document

C06RDF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

1 Purpose

C06RDF computes the discrete quarter-wave Fourier cosine transforms of m sequences of real data values.

2 Specification

```
SUBROUTINE C06RDF(DIRECT, M, N, X, WORK, IFAIL)
INTEGER          M, N, IFAIL
real           X(M*(N+2)), WORK(M*N+2*N+15)
CHARACTER*1     DIRECT
```

3 Description

Given m sequences of n real data values x_j^p , for $j = 0, 1, \dots, n-1$ and $p = 1, 2, \dots, m$, this routine simultaneously calculates the quarter-wave Fourier cosine transforms of all the sequences defined by

$$\hat{x}_k^p = \frac{1}{\sqrt{n}} \left(\frac{1}{2} x_0^p + \sum_{j=1}^{n-1} x_j^p \times \cos\left(j(2k-1)\frac{\pi}{2n}\right) \right), \quad \text{if}$$

DIRECT = 'F', or its inverse

$$x_k^p = \frac{2}{\sqrt{n}} \sum_{j=0}^{n-1} \hat{x}_j^p \times \cos\left((2j-1)k\frac{\pi}{2n}\right), \quad \text{if}$$

DIRECT = 'B', for $k = 0, 1, \dots, n-1$ and $p = 1, 2, \dots, m$.

(Note the scale factor $\frac{1}{\sqrt{n}}$ in this definition.)

A call of the routine with DIRECT = 'F' followed by a call with DIRECT = 'B' will restore the original data.

The transform calculated by this routine can be used to solve Poisson's equation when the derivative of the solution is specified at the left boundary, and the solution is specified at the right boundary (Swarztrauber (1977)).

The routine uses a variant of the fast Fourier transform (FFT) algorithm (Brigham (1974)) known as the Stockham self-sorting algorithm, described in Temperton (1983a), together with pre- and post-processing stages described in Swarztrauber (1982). Special coding is provided for the factors 2, 3, 4 and 5.

4 References

Brigham E O (1974) *The Fast Fourier Transform* Prentice-Hall

Swarztrauber P N (1977) The methods of cyclic reduction, Fourier analysis and the FACR algorithm for the discrete solution of Poisson's equation on a rectangle *SIAM Rev.* **19** (3) 490–501

Swarztrauber P N (1982) Vectorizing the FFT's *Parallel Computation* (ed G Rodrigue) 51–83 Academic Press

Temperton C (1983a) Fast mixed-radix real Fourier transforms *J. Comput. Phys.* **52** 340–350

5 Parameters

1: DIRECT – CHARACTER*1 *Input*

On entry: if the **Forward** transform as defined in Section 3 is to be computed, then DIRECT must be set equal to 'F'. If the **Backward** transform is to be computed then DIRECT must be set equal to 'B'.

Constraint: DIRECT = 'F' or 'B'.

2: M – INTEGER *Input*

3: N – INTEGER *Input*

4: X(M*(N+2)) – *real* array *Input/Output*

On entry: the data must be stored in X as if in a two-dimensional array of dimension (1 : M, 0 : N + 1); each of the m sequences is stored in a **row** of the array. In other words, if the data values of the p th sequence to be transformed are denoted by x_j^p , for $j = 0, 1, \dots, n - 1$ and $p = 1, 2, \dots, m$, then the first mn elements of the array X must contain the values

$$x_0^1, x_0^2, \dots, x_0^m, x_1^1, x_1^2, \dots, x_1^m, \dots, x_{n-1}^1, x_{n-1}^2, \dots, x_{n-1}^m.$$

The $(n + 1)$ th and $(n + 2)$ th elements of each row x_n^p, x_{n+1}^p , for $p = 1, 2, \dots, m$, are required as workspace. These $2m$ elements may contain arbitrary values as they are set to zero by the routine.

On exit: the m quarter-wave cosine transforms stored as if in a two-dimensional array of dimension (1 : M, 0 : N + 1). Each of the m transforms is stored in a **row** of the array, overwriting the corresponding original sequence. If the n components of the p th quarter-wave cosine transform are denoted by \hat{x}_k^p , for $k = 0, 1, \dots, n - 1$ and $p = 1, 2, \dots, m$, then the $m(n + 2)$ elements of the array X contain the values

$$\hat{x}_0^1, \hat{x}_0^2, \dots, \hat{x}_0^m, \hat{x}_1^1, \hat{x}_1^2, \dots, \hat{x}_1^m, \dots, \hat{x}_{n-1}^1, \hat{x}_{n-1}^2, \dots, \hat{x}_{n-1}^m, 0, 0, \dots, 0 \text{ (} 2m \text{ times)}.$$

5: WORK(M*N+2*N+15) – *real* array *Workspace*

6: IFAIL – INTEGER *Input/Output*

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

IFAIL = 2

IFAIL = 3

IFAIL = 4

7 Accuracy

Some indication of accuracy can be obtained by performing a subsequent inverse transform and comparing the results with the original sequence (in exact arithmetic they would be identical).

8 Further Comments

The time taken by the routine is approximately proportional to $nm \times \log n$, but also depends on the factors of n . The routine is fastest if the only prime factors of n are 2, 3 and 5, and is particularly slow if n is a large prime, or has large prime factors.

9 Example

This program reads in sequences of real data values and prints their quarter-wave cosine transforms as computed by C06RDF with DIRECT = 'F'. It then calls the routine again with DIRECT = 'B' and prints the results which may be compared with the original data.

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
*      C06RDF Example Program Text.
*      Mark 19 Release. NAG Copyright 1999.
*      .. Parameters ..
      INTEGER          NIN, NOUT
      PARAMETER        (NIN=5,NOUT=6)
      INTEGER          MMAX, NMAX
      PARAMETER        (MMAX=5,NMAX=20)
*      .. Local Scalars ..
      INTEGER          I, IFAIL, J, M, N
*      .. Local Arrays ..
      real            WORK(MMAX*NMAX+2*NMAX+15), X((NMAX+2)*MMAX)
*      .. External Subroutines ..
      EXTERNAL         C06RDF
*      .. Executable Statements ..
      WRITE (NOUT,*) 'C06RDF Example Program Results'
*      Skip heading in data file
      READ (NIN,*)
20  CONTINUE
      READ (NIN,*,END=120) M, N
      IF (M.LE.MMAX .AND. N.LE.NMAX) THEN
        DO 40 J = 1, M
          READ (NIN,*) (X(I*M+J),I=0,N-1)
40    CONTINUE
          WRITE (NOUT,*)
          WRITE (NOUT,*) 'Original data values'
          WRITE (NOUT,*)
          DO 60 J = 1, M
            WRITE (NOUT,99999) (X(I*M+J),I=0,N-1)
60    CONTINUE
          IFAIL = 0

*
*      Compute transform
          CALL C06RDF('Forward',M,N,X,WORK,IFAIL)
*

```

```

WRITE (NOUT,*)
WRITE (NOUT,*)
+   'Discrete quarter-wave Fourier cosine transforms'
WRITE (NOUT,*)
DO 80 J = 1, M
    WRITE (NOUT,99999) (X(I*M+J),I=0,N-1)
80  CONTINUE
*
*   Compute inverse transform
CALL C06RDF('Backward',M,N,X,WORK,IFAIL)
*
WRITE (NOUT,*)
WRITE (NOUT,*) 'Original data as restored by inverse transform'
WRITE (NOUT,*)
DO 100 J = 1, M
    WRITE (NOUT,99999) (X(I*M+J),I=0,N-1)
100 CONTINUE
GO TO 20
ELSE
    WRITE (NOUT,*) 'Invalid value of M or N'
END IF
120 CONTINUE
STOP
*
99999 FORMAT (6X,7F10.4)
END

```

9.2 Program Data

C06RDF Example Program Data

```

3 6 : Number of sequences, M, and number of values in each sequence, N
0.3854 0.6772 0.1138 0.6751 0.6362 0.1424 : X, sequence 1
0.5417 0.2983 0.1181 0.7255 0.8638 0.8723 : X, sequence 2
0.9172 0.0644 0.6037 0.6430 0.0428 0.4815 : X, sequence 3

```

9.3 Program Results

C06RDF Example Program Results

Original data values

0.3854	0.6772	0.1138	0.6751	0.6362	0.1424
0.5417	0.2983	0.1181	0.7255	0.8638	0.8723
0.9172	0.0644	0.6037	0.6430	0.0428	0.4815

Discrete quarter-wave Fourier cosine transforms

0.7257	-0.2216	0.1011	0.2355	-0.1406	-0.2282
0.7479	-0.6172	0.4112	0.0791	0.1331	-0.0906
0.6713	-0.1363	-0.0064	-0.0285	0.4758	0.1475

Original data as restored by inverse transform

0.3854	0.6772	0.1138	0.6751	0.6362	0.1424
0.5417	0.2983	0.1181	0.7255	0.8638	0.8723
0.9172	0.0644	0.6037	0.6430	0.0428	0.4815
